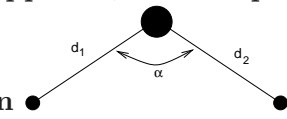


2.6. Gruppentheorie II

2.6.1 Reduzible Darstellungen von Gruppen, Basen

Reduzible Darstellungen der Punktgruppe C_{2v} am Beispiel H_2O



I. Basis: interne Verschiebungsvektoren

① Matrix für E: $E\tilde{x} = \tilde{x}$; $tr(E)=3$

$$\begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} d_1 \\ d_2 \\ \alpha \end{pmatrix} = \begin{pmatrix} d_1 \\ d_2 \\ \alpha \end{pmatrix}$$

③ Matrix für σ_{xz} ; $tr(\sigma_{xz}) = 1$

$$\begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} d_1 \\ d_2 \\ \alpha \end{pmatrix} = \begin{pmatrix} d_2 \\ d_1 \\ \alpha \end{pmatrix}$$

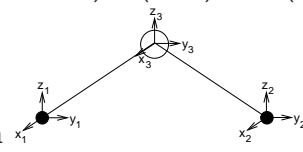
② Matrix für C_2 ; $tr(C_2) = 1$

$$\begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} d_1 \\ d_2 \\ \alpha \end{pmatrix} = \begin{pmatrix} d_2 \\ d_1 \\ \alpha \end{pmatrix}$$

④ Matrix für σ_{yz} ; $tr(\sigma_{yz}) = 3$

$$\begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} d_1 \\ d_2 \\ \alpha \end{pmatrix} = \begin{pmatrix} d_1 \\ d_2 \\ \alpha \end{pmatrix}$$

II. Basis: kartesische Verschiebungsvektoren



① Matrix für E: $E\tilde{x} = \tilde{x}$; $tr(E)=9$

$$\begin{pmatrix} 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 \end{pmatrix}$$

② Matrix für C_2 ; $tr(C_2) = -1$

$$\begin{pmatrix} -1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & -1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & -1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & -1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} x^O \\ y^O \\ z^O \\ x^{H1} \\ y^{H1} \\ z^{H1} \\ x^{H2} \\ y^{H2} \\ z^{H2} \end{pmatrix} = \begin{pmatrix} -x^O \\ -y^O \\ z^O \\ -x^{H2} \\ -y^{H2} \\ z^{H2} \\ -x^{H1} \\ -y^{H1} \\ z^{H1} \end{pmatrix}$$

③ Matrix für σ_{xz} ; $tr(\sigma_{xz}) = 1$

$$\begin{pmatrix} 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & -1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & -1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 \end{pmatrix}$$

④ Matrix für σ_{yz} ; $tr(\sigma_{yz}) = 3$

$$\begin{pmatrix} -1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & -1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & -1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 \end{pmatrix}$$

III. Basis: Atomorbitale

① Matrix für E ($tr(E)=6$)

$$\begin{pmatrix} 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1s(H1) \\ 1s(H2) \\ 2s(O) \\ 2p_z(O) \\ 2p_x(O) \\ 2p_y(O) \end{pmatrix}$$

② Matrix für C_2 ($tr(C_2)=0$)

$$\begin{pmatrix} 0 & 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & 0 & 0 & -1 \end{pmatrix} \begin{pmatrix} 1s(H1) \\ 1s(H2) \\ 2s(O) \\ 2p_z(O) \\ 2p_x(O) \\ 2p_y(O) \end{pmatrix}$$

③ Matrix für $\sigma_v(xz)$ ($tr(\sigma_v(xz))=2$)

$$\begin{pmatrix} 0 & 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & -1 \end{pmatrix} \begin{pmatrix} 1s(H1) \\ 1s(H2) \\ 2s(O) \\ 2p_z(O) \\ 2p_x(O) \\ 2p_y(O) \end{pmatrix}$$

④ Matrix für $\sigma_v(yz)$ ($tr(\sigma_v(yz))=4$)

$$\begin{pmatrix} 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1s(H1) \\ 1s(H2) \\ 2s(O) \\ 2p_z(O) \\ 2p_x(O) \\ 2p_y(O) \end{pmatrix}$$